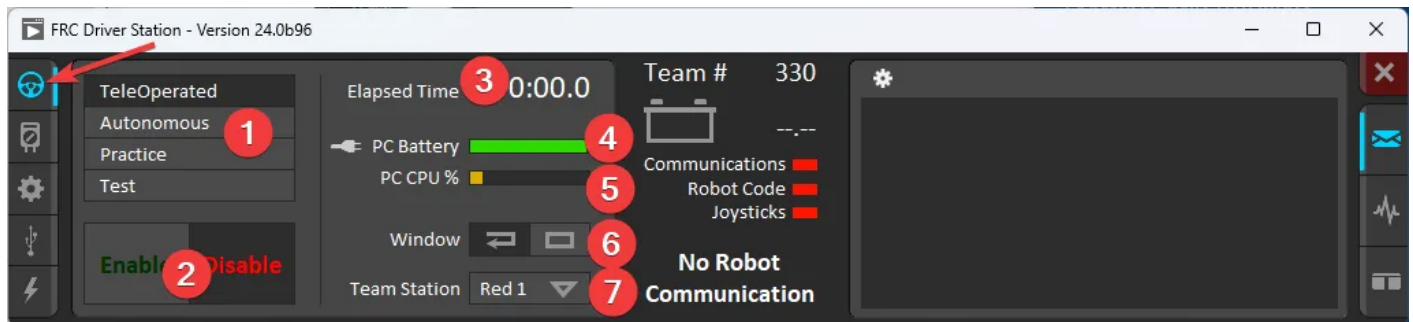
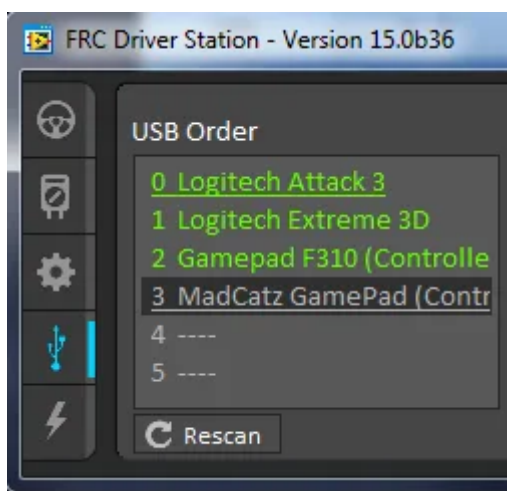


Using the Driver Station

Being able to operate the driver station (DS) is necessary to operate the robot. This will guide you through the things you need to know when using the DS at demos.

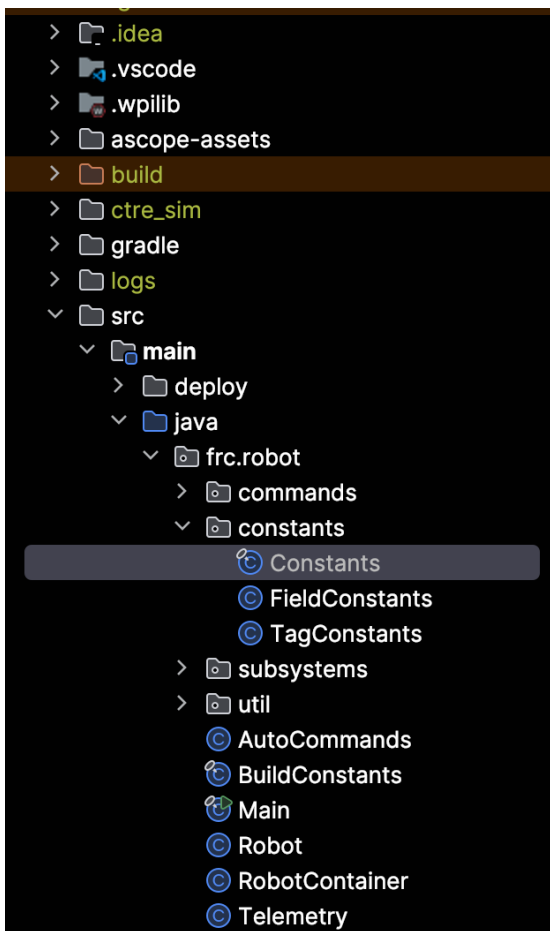


This is the operation tab. Selecting different modes on the menu at 1 will allow you to switch between them. At demos, however, you will likely only be on the *TeleOperated* mode for safety reasons. The only other item you need to know on this menu is 2, which allows you to *Enable* and *Disable* it whenever necessary.



This is the devices tab. Different controllers (primary and secondary/gigastation) require different ports. You can adjust the different ports by holding a device and dragging it to the correct port. You can check what the correct port is in the code as follows:

1. First, go to the *Constants.java* file in IntelliJ:



2. Then scroll to the point where the ports are set for the controllers:

```
public static final int PRIMARY_XBOX_CONTROLLER_PORT = 0; 1 usage
public static final String CANIVORE_BUS = "canivoreBus"; no usages
public static final String RIO_BUS = "rio"; 9 usages
public static final int SECONDARY_XBOX_CONTROLLER_PORT = 1; 1 usage
public static final int GIGA_PORT = 3; 1 usage
```

Now, you can drag the controllers to the correct port in the devices tab based on what you see in the *Constants.java* file. Happy demoing!